

Monte Carlo Methods Convergence

Dieter W. Heermann

Heidelberg University

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1. Introduction



- What does this mean if we calculate the time average of an observable A, by necessity can cover only a finite observation time?
- Let us consider the statistical error for *n* successive observations A_i , i = 1, ..., n:

$$\left\langle (\delta A)^2 \right\rangle = \left\langle \left[n^{-1} \sum_{i=1}^n \left(A_i - \langle A \rangle \right)^2 \right] \right\rangle \quad .$$
 (1)

In terms of the autocorrelation function for the observable A

$$\phi_{A}(t) = \frac{\langle A(0)A(t) \rangle - \langle A \rangle^{2}}{\langle A^{2} \rangle - \langle A \rangle^{2}}$$
(2)

We define two characteristic correlation times.

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Exponential autocorrelation time



Typically we expect that (asymptotically, for large *t*) one gets an exponential behavior

$$\Phi_A(t) \propto \exp\left(-\frac{t}{\tau_{A,exp}}\right)$$
 (3)

- We do expect, though, that the complete expression involves a sum over several such terms; here we consider only the asymptotically most leading term with largest autocorrelation time.
- Integrated autocorrelation time

$$\tau_A^{int} = \int_0^\infty \phi_A(t) dt \quad . \tag{4}$$

We can rewrite the statistical error as



$$\left\langle (\delta A)^2 \right\rangle \cong \frac{2\tau_A}{n\delta t} \left[\left\langle A^2 \right\rangle - \left\langle A \right\rangle^2 \right] \quad ,$$
 (5)

where δt is the time between observations, i.e., $n\delta t$ is the total observation time τ_{obs} .

- We notice that the error does not depend on the spacing between the observations but on the total observation time.
- Also the error is not the one which one would find if all observations were independent.
- The error is enhanced by the characteristic (integral) correlation time between configurations.
- Only an increase in the sample size and/or a reduction in the characteristic correlation time τ_A can reduce the error.

Critical Slowing Down



Problem: Critical Slowing Down

■ For local dynamics, the autocorrelation between successively generated configurations varies with the linear system size *L* as

$$\tau \propto L^{z}$$
 (6)

with the dynamical critical exponent $z \neq 0$, while for those with non-local dynamics z = 0, i.e., a logarithmic behaviour can occur

 \blacksquare In the thermodynamic limit one finds for the intrinsic relaxation time: τ



$$\tau \sim \xi^z \sim (1 - \tau/\tau_c)^{-\nu z}$$

(Rule $\xi \leftrightarrow L$)

$$\Rightarrow au_{max} \sim L^z \ (T = T_c)$$

$$< (\delta M)^2 > = \frac{2\tau_{max}}{t_{obs}} \left[< M^2 >_{T_c} - < |M| >^2_{T_c} \right]$$
$$= \frac{2\tau_{max} \chi_{max} k_B T_c}{t_{obs} L^{\alpha}} \sim L^{z+\gamma/\nu-d}/t_{obs}$$

since $L^{z+\gamma/\nu}\approx L^y$ ($d\leq 4$) we have: To raise the precision by a factor of 10 we need 10^y more computing time.

Spatial Averaging



Now that we know how the statistical error for an observable A depends on the finite observation time, we can ask for the dependence on the finite system size. For this we define

$$\Delta(n,L) = \sqrt{\left(\langle A^2 \rangle_L - \langle A \rangle_L^2\right)/n} \quad . \tag{7}$$

Here *L* is the linear dimension of the system. Note that we write $\langle . \rangle_L$ for the average. This is meant as the average with respect to the finite system size. How does this error depend on *L*.



Recall that for thermodynamic equilibrium, for a system of infinite size on observation suffices to obtain A.



- In other words, if $L \to \infty$ then $\Delta(n, L)$ must go to zero, regardless of n. Or, if we increase the system size then the effective number of observations should increase.
- Let *L* be the system size and *L'* the new one which we obtain by a scale factor *b* with b > 1 : L' = bL.
- The number of effective observations will change to $n' = b^{-d}n$ where d is the dimensionality.

More formally we can express the idea by

$$\Delta(n,L) = \Delta(n',L') = \Delta(b^{-d}n,bL)$$
(8)

 \blacksquare We can work out this expression using the definition of Δ and find

$$\langle A^2 \rangle_L - \langle A \rangle_L^2 \propto L^{-x}, \quad 0 \le x \le d$$
 (9)

- In the case where x = d we call the observable A strongly self-averaging and in the cases 0 < x < d, weakly self-averaging.
- As we increase *L*, *b* tends to a finite value, independent of *L*.

