

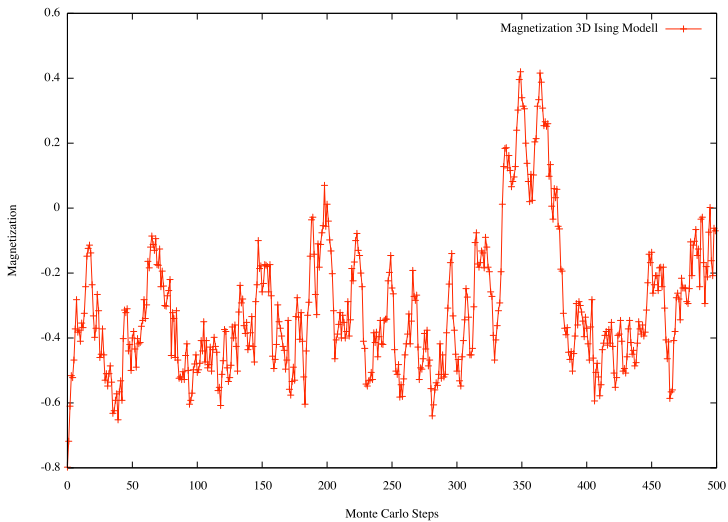
# Convergence

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Monte Carlo Methods

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- What does this mean if we calculate the time average of an observable  $A$ , which by necessity can cover only a finite observation time?
- Let us consider the statistical error for  $n$  successive observations  $A_i, i = 1, \dots, n$ :

$$\langle (\delta A)^2 \rangle = \left\langle \left[ n^{-1} \sum_{i=1}^n (A_i - \langle A \rangle)^2 \right] \right\rangle . \quad (1)$$

- In terms of the autocorrelation function for the observable  $A$

$$\phi_A(t) = \frac{\langle A(0)A(t) \rangle - \langle A \rangle^2}{\langle A^2 \rangle - \langle A \rangle^2} \quad (2)$$

We define two characteristic correlation times.

## • Exponential autocorrelation time

- Typically we expect that (asymptotically, for large  $t$ ) one gets an exponential behavior

$$\Phi_A(t) \propto \exp\left(-\frac{t}{\tau_{A,exp}}\right) \quad (3)$$

- We do expect, though, that the complete expression involves a sum over several such terms; here we consider only the asymptotically most leading term with largest autocorrelation time.

## • Integrated autocorrelation time

$$\tau_A^{int} = \int_0^\infty \phi_A(t) dt \quad . \quad (4)$$

- We can rewrite the statistical error as

$$\langle (\delta A)^2 \rangle \cong \frac{2\tau_A}{n\delta t} \left[ \langle A^2 \rangle - \langle A \rangle^2 \right] , \quad (5)$$

where  $\delta t$  is the time between observations, i.e.,  $n\delta t$  is the total observation time  $\tau_{\text{obs}}$ .

- We notice that the error does not depend on the spacing between the observations but on the total observation time.
- Also the error is not the one which one would find if all observations were independent.
- The error is enhanced by the characteristic (integral) correlation time between configurations.
- Only an increase in the sample size and/or a reduction in the characteristic correlation time  $\tau_A$  can reduce the error.

# Critical Slowing Down

- Problem: Critical Slowing Down
  - For local dynamics, the autocorrelation between successively generated configurations varies with the linear system size  $L$  as

$$\tau \propto L^z \quad (6)$$

with the dynamical critical exponent  $z \neq 0$ , while for those with non-local dynamics  $z = 0$ , i.e., a logarithmic behaviour can occur

- In the thermodynamic limit one finds for the intrinsic relaxation time:  
 $\tau$

$$\tau \sim \xi^z \sim (1 - \tau/\tau_c)^{-\nu z}$$

(Rule  $\xi \leftrightarrow L$ )

$$\Rightarrow \tau_{max} \sim L^z \quad (T = T_c)$$

$$\begin{aligned} \langle (\delta M)^2 \rangle &= \frac{2\tau_{max}}{t_{obs}} \left[ \langle M^2 \rangle_{T_c} - \langle |M| \rangle_{T_c}^2 \right] \\ &= \frac{2\tau_{max} \chi'_{max} k_B T_c}{t_{obs} L^\alpha} \sim L^{z+\gamma/\nu-d} / t_{obs} \end{aligned}$$

since  $L^{z+\gamma/\nu} \approx L^y$  ( $d \leq 4$ ) we have:

To raise the precision by a factor of 10 we need  $10^y$  more computing time.

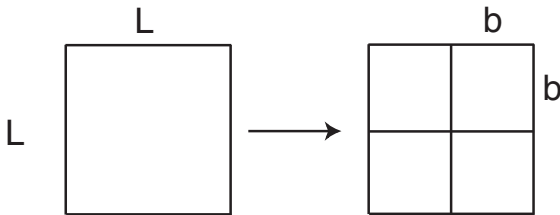


# Spatial Averaging

- Now that we know how the statistical error for an observable  $A$  depends on the finite observation time, we can ask for the dependence on the finite system size. For this we define

$$\Delta(n, L) = \sqrt{\left(\langle A^2 \rangle_L - \langle A \rangle_L^2\right) / n} \quad (7)$$

Here  $L$  is the linear dimension of the system. Note that we write  $\langle \cdot \rangle_L$  for the average. This is meant as the average with respect to the finite system size. How does this error depend on  $L$ .



- Recall that for thermodynamic equilibrium, for a system of infinite size one observation suffices to obtain  $A$ .
- In other words, if  $L \rightarrow \infty$  then  $\Delta(n, L)$  must go to zero, regardless of  $n$ . Or, if we increase the system size then the effective number of observations should increase.
- Let  $L$  be the system size and  $L'$  the new one which we obtain by a scale factor  $b$  with  $b > 1$  :  $L' = bL$ .
- The number of effective observations will change to  $n' = b^{-d}n$  where  $d$  is the dimensionality.

- More formally we can express the idea by

$$\Delta(n, L) = \Delta(n', L') = \Delta(b^{-d}n, bL) \quad (8)$$

- We can work out this expression using the definition of  $\Delta$  and find

$$\langle A^2 \rangle_L - \langle A \rangle_L^2 \propto L^{-x}, \quad 0 \leq x \leq d \quad . \quad (9)$$

- In the case where  $x = d$  we call the observable  $A$  strongly self-averaging and in the cases  $0 < x < d$ , weakly self-averaging.
- As we increase  $L$ ,  $b$  tends to a finite value, independent of  $L$ .