

Multi-Grid-Monte-Carlo

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Monte Carlo Methods

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- Local Monte Carlo methods generate a new value ϕ'_x at x of the lattice Λ assuming a fixed $\phi_{y \neq x}$

$$\mathcal{H}'(\phi'_x, \{\phi_y\}_{y \neq x}) \leftarrow \mathcal{H}(\phi_x, \{\phi_y\}_{y \neq x})$$

- We have encountered the Metropolis, Glauber and the Heat-Bath Monte Carlo Method as examples.
- In contrast to the global methods like the cluster algorithms they only introduce changes on a small length scale.
- If there is an inherent large length scale in the problem one encounters the problem of *critical slowing down*.

- A similar problem arises solving algebraic equations:

$$A\phi = f$$

- Let us try an iterative method

$$\phi^{(n+1)} = M\phi^{(n)} + g$$

- We want $A\phi = f$ to be a fix point of the iteration

$$\begin{aligned}\phi &= M\phi + g \\ \Leftrightarrow A^{-1}f &= MA^{-1}f + g \\ \Leftrightarrow g &= (I - M)A^{-1}f\end{aligned}$$

- Partition $A = N - P$, then with $M = N^{-1}P$

$$g = (1 - N^{-1}P)A^{-1}f = N^{-1}(N - P)A^{-1}f = N^{-1}f$$

- With this we find

$$\phi^{(n+1)} = M\phi^{(n)} + N^{-1}f$$

- the properties of the method are determined by the matrix M .
- Let us look at the standard decomposition

$$A = L + D + U$$

(L = left lower, U = right upper triangular matrix, D = diagonal matrix).

- Choose $N = D + L$, $P = -U$, then

$$\phi^{(n+1)} = \underbrace{-(D + L)^{-1}U}_{=:M} \phi^{(n)} + (D + L)^{-1}f$$

- The above is known as the **Gauss-Seidel method**.
- component wise:

$$\phi_i^{(n+1)} = \frac{1}{Q_{ii}} \left(f_i - \sum_{j=1}^{i-1} a_{ij} \phi_j^{(n+1)} - \sum_{j=i+1}^n a_{ij} \phi_j^{(n)} \right)$$

- The Gauss-Seidel method is a **single step method**.
- This corresponds to a local update Monte Carlo method.
- To strengthen the point, let us look at

$$-\Delta\phi = f \quad x \in \mathbf{R}^d \quad \text{on the lattice } \Lambda \subset \mathbf{Z}^d$$

with Dirichlet boundary conditions $\phi_x \equiv 0 \quad x \notin \Omega$

$$(-\Delta\phi)_x := 2d\phi_x - \sum_{x': |x-x'|=1} \phi_{x'} = f_x \Leftrightarrow A\phi = f \quad |\Lambda| = n$$

- This is equivalent to

$$\begin{aligned} \min! &= \mathcal{H}(\phi) := \frac{1}{2} \sum_{\langle xy \rangle} (\phi_x - \phi_y)^2 - \sum_x f_x \phi_x & \phi_x \in \mathbf{R} \\ &\Leftrightarrow \frac{1}{2}(\phi, A\phi) - (f, \phi) = \min! \end{aligned}$$

- The matrix is block diagonal and positive definite

$$\phi A \phi \geq 0 \quad \forall \phi \neq 0$$

and symmetric

- We claim that

- $\mathcal{H}(\phi)$ has an absolute minimum, i.e.,

$$\exists \phi_0 \in \mathbf{R}^n \quad \forall \phi \in \mathbf{R}^n : \quad \mathcal{H}(\phi_0) \leq \mathcal{H}(\phi)$$

- ϕ_0 is the unique solution to $A\phi = f$

- Proof:

Since A is positive definite $A\phi = f$ is the unique solution. Let ϕ_0 be the solution and $\phi = \psi - \phi_0 \in \mathbf{R}^n$. Then

$$\begin{aligned}
 \mathcal{H}(\psi) &= \mathcal{H}(\phi + \phi_0) \\
 &= \frac{1}{2}(\phi + \phi_0, A(\phi + \phi_0)) - (f, \phi + \phi_0) \\
 &= \frac{1}{2}(\phi, A(\phi + \phi_0)) + \frac{1}{2}(\phi_0, A(\phi + \phi_0)) - (f, \phi) - (f, \phi_0) \\
 &= \frac{1}{2}(\phi, A\phi) + \frac{1}{2}(\phi, A\phi_0) + \frac{1}{2}(\phi, A\phi_0) + \frac{1}{2}(\phi_0, A\phi_0) - (f, \phi) - \\
 &= \mathcal{H}(\phi_0) + \underbrace{\frac{1}{2}(\phi, A\phi)}_{\geq 0}
 \end{aligned}$$

since A is symmetric, hence $(A\phi, \psi) = (\phi, A\psi)$.

- The solution of the Poisson equation is equivalent to the minimization of a Hamiltonian.

- Back to the properties of M ! Consider the error

$$e^{(n)} := \phi^{(n)} - \phi.$$

- We have

$$\begin{aligned} e^{(n+1)} &= \phi^{(n+1)} - \phi = M\phi^{(n)} + N^{-1}f - A^{-1}f \\ &= M\left(e^{(n)} + \phi\right) + N^{-1}f - A^{-1}f \\ &= Me^{(n)} + \underbrace{M\phi + N^{-1}f - A^{-1}f}_{=0} \end{aligned}$$

- from which follows that $e^{(n)} = M^n e^{(0)}$
- Let $\rho(M) := \lim_{n \rightarrow \infty} \|M^n\|^{1/n}$ be the spectral radius

$$\text{EW} < 1 \leftrightarrow \rho(M) < 1$$

- And further

$$\|\phi^{(n)} - \phi\| \leq Kn^P \rho(M)^n$$

- **Problem:** How near is $\rho(M)$ to 1?
- Let us look at a generalization of the Gauss-Seidel method

$$N = L + \frac{1}{\omega}D, \quad P = \frac{1}{\omega}(1 - \omega)D - U \quad \omega \in (0, 2)$$

- note that $\omega = 1$ is the Gauss-Seidel-method.

$$\Phi^{(n+1)} = (L + \frac{1}{\omega}D)^{-1}(\frac{1}{\omega}(1 - \omega)D - U)\Phi^{(n)} + (L + \frac{1}{\omega}D)^{-1}f$$

- this method is known as the **damped Jacobi-method** or **SOR** (successive overrelaxation).

- One can show that

$$\omega_{\text{opti}} = \frac{2}{1 + \sin \frac{\pi}{L+1}}, \lambda_{ij} = \frac{1}{2} \left(\cos \frac{i\pi}{L+1} + \cos j\pi L + 1 \right)$$

$$\rho(M\omega_{\text{opti}}) = \frac{\cos^2 \frac{\pi}{L+1}}{\left(1 + \sin \frac{\pi}{L+1}\right)^2}$$

- if one restricts the integration to a square lattice \mathbb{Z}^2
- If one expands sin und cos to first order and traces L then

$$\rho(M\omega_{\text{opti}}) = \frac{\cos^2 \frac{\pi}{L+1}}{\left(1 + \sin \frac{\pi}{L+1}\right)^2} \sim O\left(\frac{\left(1 - \frac{1}{L^2}\right)^2}{\left(1 + \frac{1}{L^2}\right)^2}\right) \sim 1 - O\left(\frac{1}{L^2}\right)$$

- A critical slowing down arises as happens at the critical point

$$(-\Delta\phi)_x := 2d\phi_x - \sum_{x':|x-x'|=1} \phi_{x'} = f_x$$

- Poisson equation, $\Omega \subset \mathbf{Z}^d$, $x \notin \Omega$: $\phi_x \equiv 0$
- linear system of equations $A\phi = f$
- $\phi^{(n+1)} = M\phi^{(n)} + Nf$

$$\phi_x^{(n+1)} = (1 - \omega)\phi_x^{(n)} + \frac{\omega}{2d} \left[\sum_{x':|x-x'|=1} \phi_{x'} + f_x \right]$$

- In general: $A\phi = f$, A regular, $A : U \rightarrow V$, where $U, V \in \mathbf{VR}(n)$
 - Let $U_M := U, U_{M-1}, \dots, U_0$
and $V_M := V, V_{M-1}, \dots, V_0$ two sequences of Spaces,
where $\dim U_l = \dim V_l =: N_l, \forall 0 \leq l \leq M$,
 $n = N_M > N_{M-1} > \dots > N_0$.
 - Let $r_{l-1,l} : V_l \rightarrow V_{l-1}, 1 \leq l \leq M$ be restriction operators
 - Let $p_{l,l-1} : U_{l-1} \rightarrow U_l, 1 \leq l \leq M$ be prolongation operators
 - Let $A_l : U_l \rightarrow V_l, 0 \leq l \leq M-1$
 - Smothers $S_l : U_l \times V_l \rightarrow U_l, 0 \leq l \leq M$,
 $S_l(\phi'_0, f_l) = \phi''_l$ approximate solution

- 1: **procedure** mym(l, ϕ, f)
 - 2: $\phi \leftarrow S_l^{pre}(\phi, f)$
 - 3: **if** ($l > 0$) **then**
 - 4: $d \leftarrow -r_{l-1,l} \overbrace{(A_l \psi - f)}^{\text{Residual}}$
 - 5: $\phi \leftarrow 0$ starting value
 - 6: **for** $j = 1$ until γ_l **do**
 - 7: mym($l - 1, \psi, d$)
 - 8: **end for**
 - 9: $\phi \rightarrow \phi + P_{l,l-1} \psi$
 - 10: $\phi \rightarrow S_l^{post}(\phi, f)$
 - 11: **end if**
 - 12: **end procedure**
- γ_l number of iterations, $A_{l-1} \psi = d$

- Example

- Trivial restriction $(r_{l-1,l}\phi_l)_x \equiv (\phi_l)_x, \forall x \in \Omega_{l-1} \subset \Omega_l$
- Averaging

$$(r_{l-1,l}\phi_l)_x = \frac{1}{4} [(\phi_l)_{x_1+1/2, x_2+1/2} + \dots]$$

or nine point averaging

$$\begin{bmatrix} \frac{1}{16} & \frac{1}{8} & \frac{1}{16} \\ \frac{1}{8} & \frac{1}{4} & \frac{1}{8} \\ \frac{1}{16} & \frac{1}{8} & \frac{1}{16} \end{bmatrix}$$

- piecewise constant insertion

$$(p_{l,l-1}\phi_{l-1})_{x_1 \pm 1/2, x_2 \pm 1/2} = (\phi_{l-1})_{x_1, x_2} \quad \forall x \in \Omega_{l-1}$$

- piecewise linear insertion

$$\begin{bmatrix} \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{2} & 1 & \frac{1}{2} \\ \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \end{bmatrix}$$

- $A_{l-1} = r_{l-1,l} A_l p_{l,l-1}$ Galerkin definition
- $\rho_l = \rho > 1, \forall 1 < l < M$

- Non-linear case

$U \in V\mathbb{R}(n)$, $\mathcal{H} : U \rightarrow \mathbb{R}$ Hamilton function.

Assume, $\exists! \mathbf{x} \in U : \mathcal{H} = \min$

$U_M := U, U_{M-1}, \dots, U_0$

$\dim U_l =: N_l$

$N = N_M > N_{M-1} > \dots > N_0$

Prolongation operators $P_{l,l-1} : U_{l-1} \rightarrow U_l$

Smothers $S_l : U_l \times \mathcal{H}_l \rightarrow U_l \quad 0 \leq l \leq M$

Cycle control parameter $\gamma_l \geq 1, \quad 1 \leq l \leq M$

- 1: **procedure** ulmym(l, ϕ, H_l)
- 2: $\phi \rightarrow S^{pre}(\phi, H_l)$
- 3: **if** $l > 0$ **then**
- 4: Compute $H_{l-1}(\cdot) := H_l(\phi + p_{l,l-1}\cdot)$
- 5: $\psi \rightarrow 0$
- 6: **for** $j=1$ **until** γ_l **do** ulmym($l - 1, \psi, H_{l-1}$)
- 7: $\phi \rightarrow \phi + p_{l,l-1}\psi$
- 8: **end if**
- 9: $\phi \rightarrow S_l^{post}(\phi, H_l)$
- 10: **end procedure**

“Compute H_{l-1} ”:

$$H_l(\phi) = \frac{\alpha}{2} \sum_{|x-x'|=1} (\phi_x - \phi_{x'})^2 + \sum_x V_x(\phi_x)$$

$$V_x(\phi_x) = \lambda \phi_x^4 + u_x \phi_x^3 + A_x \phi_x^2 + h_x \phi_x$$

Assume: $p_{l,l-1}$ piecewise constant, need to compute

$$H_{l-1}(\psi) := H_l(\phi + p_{l,l-1}\psi)$$

$$\rightarrow H_{l-1}(\psi) = \frac{\alpha'}{2} \sum_{|y-y'|=1} (\psi_y - \psi_{y'})^2 + \sum_y V'_y(\psi_y) + \text{const}$$

$$V'_y(\psi_y) = \lambda' \psi_y^4 + k'_y \psi_y^3 + A'_y \psi_y^2 + h'_y \psi_y$$

$$\alpha' := 2^{d-1} \alpha$$

$$\lambda' := 2^d \lambda$$

$$k'_y := \sum_{x \in B_y} (4\lambda \phi_x + K_x) \quad |B_y| = 2^d$$

$$A'_y := \sum_{x \in B_y} (6\lambda \phi_x^2 + 3k_x \phi_x + A_x)$$

$$h'_y := \sum_{x \in B_y} (4\lambda \phi_x^3 + 3k_x \phi_x^2 + 2A_x \phi_x + h_x)$$

Construct \mathcal{H}_l such that

$$H_l \in \mathcal{H}_l \text{ und } \phi \in U_l \rightarrow H_{l-1} \in \mathcal{H}_{l-1}$$

Let U_α , $U = \bigcup_\alpha U_\alpha$, $\alpha, \beta \in \mathcal{O}$, $\alpha \neq \beta$ $U_\alpha \cap U_\beta = \emptyset$

$$d\mu(\phi) = \int d\nu(\phi|\alpha)d\rho(\alpha)$$

$\rho(\cdot)$ probability measure of \mathcal{I}




$d\nu(\cdot|\alpha)$ probability measure of U_α , conditioned probability distribution of $d\mu(\phi)$ at fixed ϕ in U_α

Let $P(\phi \rightarrow \phi')$ be a transition probability

$$\int d\nu(\phi|\alpha)P(\phi \rightarrow \phi') = d\nu(\phi'|\alpha)$$

$$\Rightarrow \int d\mu(\phi)P(\phi \rightarrow \phi') = d\mu(\phi')$$

Multi-Grid Monte Carlo is a special form of the partial resampling.

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